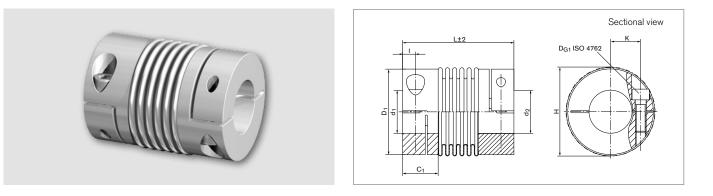


Metal Bellows Couplings RINGFEDER[®] GWB AKD

Metal bellows coupling with clamping hubs



Size	L	d ₁ ;d ₂ min-max	C ₁	D ₁	н	I	к
	mm	mm	mm	mm	mm	mm	mm
18	71	8 - 26	19,2	45	47	6	18
30	73	10 - 30	24,1	55	56	8	20
60	89	12 - 35	28,6	64	67	10	24
80	103	14 - 42	32,4	80	84	12	28
150	103	14 - 42	32,4	80	84	12	28
200	113	22 - 46	36,9	90	93	13	31
300	115	24 - 60	36,9	110	110	13	39
500	122	35 - 64	40,4	119	122	15	43
800	140	40 - 75	45,2	132	139	17	48

Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings < dmin. Types with borings < dmin, however, can be supplied.

Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

Size	т	n _{max}	Cr	Ca	C _{Tdyn}	∆K _a	∆K _w	∆K _r	J	D _{G1}	T _{A1}	Gw
	Nm	1/min	N/mm	N/mm	10 ³ Nm/rad	mm	degree	mm	10 ⁻³ kgm ²	mm	Nm	kg
18	22	12700	85	40	6	0,5	1,5	0,2	0,06	1 x M5	6	0,143
30	36	10200	220	30	25	0,5	1,5	0,2	0,1	1 x M6	12	0,263
60	75	8600	330	55	50	0,5	1,5	0,2	0,3	1 x M8	30	0,434
80	95	6800	400	55	75	0,5	1,5	0,2	0,9	1 x M10	60	0,792
150	180	6800	600	85	100	0,5	1,5	0,2	0,9	1 x M10	85	0,792
200	240	6300	450	85	120	0,5	1,5	0,2	1,5	1 x M12	100	1,117
300	360	5900	1500	150	280	0,5	1,5	0,2	3,2	1 x M12	120	1,495
500	600	4900	1000	85	310	1	1,5	0,2	4,9	1 x M14	190	2,038
800	800	5000	6200	100	780	3,5	1,5	0,35	17,5	2 x M16	250	6,06

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EN Tech Paper

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Metal Bellows Couplings RINGFEDER[®] GWB AKD

Transmissible torque T [Nm]

Size	Ø8	Ø9	Ø10	Ø11	Ø12	Ø14	Ø15	Ø16	Ø18	Ø20	Ø25	Ø30	Ø35	Ø40	Ø45	Ø50	Ø55	Ø60	Ø64	Ø70	Ø75
18	18	20	22	22	22	22	22	22	22	22	22										
30			36	36	36	36	36	36	36	36	36	36									
60					75	75	75	75	75	75	75	75	75								
80							95	95	95	95	95	95	95	95							
150							180	180	180	180	180	180	180	180							
200											240	240	240	240	240						
300											360	360	360	360	360	360	360	360			
500													600	600	600	600	600	600	600		
800														800	800	800	800	800	800	800	800

Explanation

L	= Total length	к	= Distance shaft axis - clamping screw axis	$\Delta \mathbf{K_r}$	= Max. permissible radial misalignment
d ₁ ;d _{2min}	 Min. bore diameter d₁/d₂ 	т	= Transmissible torque at given T_A	J	= Total moment of inertia
d ₁ ;d _{2max}	= Max. bore diameter d ₁ /d ₂	n _{max}	= Max. rotation speed	n _{Sc1}	= Quantity of screws D_{G1}
C ₁	 Guided length in hub bore 	Cr	= Radial spring stiffness	D _{G1}	= Thread
D ₁	= Outer diameter	Ca	= Axial spring stiffness	T _{A1}	= Tightened torque of clamping screw D_{G1}
н	= Clearance diameter	C _{Tdyn}	= Dynamic torsional stiffness	Gw	= Weight
I	= Distance between center screw hole	ΔK_a	= Max. permissible axial misalignment		
	and hub end	$\Delta \textbf{K}_{\textbf{w}}$	= Max. permissible angular misalignment		

Ordering example

Series/Size	Bore diameter d ₁	Bore diameter d_2	Further details
AKD 150	30	35	*

* Keyway or stainless steel

More information about **RINGFEDER®** GWB AKD on www.ringfeder.com

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